# Woojay Poynter

# Software Engineer

Full-stack Web Developer & Embedded Firmware Engineer



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Wien, Austria

github.com/woojay (7)

## WORK EXPERIENCE

# Chief Technology Officer / Partner modis.io

02/2016 - Present

Wien, AT

Digital & Pyhsical Hybrid Security Product Manufacturer

#### Achievements/Tasks

- Develop front-end web application with HTML, CSS, Javascript, jQuery, SASS, and Bootstrap.
- Develop REST-ful back-end web application with Python, SQL, and Linux.
- Develop and test ARM microcontroller firmware in C using AC6 and Atollic IDE.
- Test firmware reliability and RTOS performance with JLink debugger and Segger SystemView.
- Build and test custom Linux image using Docker and Vagrant for cross-development targeted for Raspberry Pi.
- Utilize Git, Github, Gitlab, Slack, Eclipse, PyCharm, and STM32CubeMX for daily production management.

### **Professor**

## Southwestern Oregon Community College

11/2008 - 02/2017

Oregon, USA

#### Achievements/Tasks

- Instruct all culinary classes including international cuisine and garde-manger classes for 15-months AAS Culinary Arts program.
- Instruct all pastry and baking classes including nutrition, sanitation, bread baking, pastry and confection arts for 15-months AAS Baking & Pastry program.
- Received a gold medal in individual category in 2012 Olympiade der Köche in Erfurt, Germany.

## **EDUCATION**

# M.A. in Economics, Honors University of Oklahoma

1999 – 2002

#### Courses

Information Management, Linear Regression, and Urban Development

Oklahoma, USA

# B.S. in Computer, Science, Cum Laude Michigan Technological University

1992 – 1996

Michigan, USA

#### Courses

 Software Engineering, Algorithms, Computer Graphics, Database, and Object-oriented Programming

## **SKILLS**



# **PERSONAL PROJECTS**

Materialize CSS Front-End Portfolio Web Pages (2018)

- Wire-frame demonstration webpages for the latest Materialize CSS framework using Javascript, jQuery, HTML5, CSS3, SASS, and Git.
- http://woojay.github.io for more.

#### Mesh ISM-band RF Network (2018)

Implemented low-cost autonomous wireless mesh network using low-cost ATMEL microcontrollers

## Self-balancing Two-Wheeled Robot (2015)

MEMS and Arduino controlled self-balancing robot using PID

#### LANGUAGES

English	
Korean	
German / A1	

### INTERESTS

